

*Race Technology*

# CAN Interface

Instruction manual



Version 2.3

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## **Introduction**

The Race Technology CAN interface is a small unit (35 x 24 x 8mm) which can be configured to receive up to 15 CAN messages and retransmit them using the Race Technology serial protocol. The output data from this unit can be used directly with a PC to show CAN data, with a dashboard such as the DASH1 or DASH2 to monitor in-vehicle information, or with a data logger to log the data and further analyse on a PC.

## **Parts Supplied**

The CAN interface is supplied with the following components. Please take a moment to check that you have all of these items and inform Race Technology of any shortages immediately:

- CAN interface unit with 3 x 9 way connectors
- Null modem serial cable – for configuration and reflashing. Reflashing is not required during normal operation and should only be carried out with explicit instructions to do so from Race Technology
- Terminator connector
- Software CD
- Instruction manual

## **Before You Begin**

In order for the DL1 or DL2 data logger and DASH1 or DASH2 display to function correctly with the CAN interface it is first necessary to ensure that all units are using the most up to date version of their respective firmware. Display units and data loggers shipped with the CAN interface will already have the correct firmware version installed, but if you have received the CAN interface separately to use with your existing data logger and/or display unit you will need to update the firmware on these units. Please contact Race Technology to obtain the latest firmware upgrades for the data loggers and display units.

Reflashing procedures for these units are available in the documentation supplied along with the units. If you are in any doubt about reflashing procedure, please contact Race Technology before proceeding.

## Description of Operation

The configuration of the interface module is performed using the CAN configuration software, which is a standard part of the Race Technology V7 software installation. This can be found in the configuration section of the installation. When started, the CAN Configuration software will look like this:

	RT message User Name (Default name)	CAN ID length	CAN ID (use 0x for Hex)	Filter Loc	Filter Val	Start bit	Length (bits)	Value type	Byte order	Scale factor	Offset	Exponent (for time only)
1												
2												
3												
4												
5												
6												
7												
8												
9												
10												
11												
12												
13												
14												
15												

n/a

Can Baud Rate: 500 kbit

IMPORTANT: Configuring the CAN to serial adapter requires the CAN protocol information to be available and some knowledge of the CAN system. Race Technology are happy to assist in doing this if required, but in most cases this support will be chargeable. For more information about this service, please contact sales@race-technology.com.

Send configuration: Serial Port 1 [Send now!]

Enable OBD mode

Enabling OBD mode uses Channel 15 of the CAN adapter data stream, so this will not be available for general use. In OBD mode the baud rate cannot be manually set - it is automatically requested and measured from the vehicle

IMPORTANT: If OBD is enabled, and OBD is not available then the CAN adapter will not be able to establish communications.

## RT message

These are the available output messages. All output messages must be scaled for a value from 0-65535 for unsigned and -32768 to 32767 for signed values. Output messages are split in to the following groups

Temperatures (25 channels)	Time (12 channels)
Percentages (31 channels)	Frequencies (4 channels)

With the exception of the time channels, all channels are of exactly the same data format, so can easily be used for any other function.

## CAN ID length

There are two CAN addressing modes in common use; 11bit and 29bit addressing. This field must be set to the same type of addressing mode as the messages to be decoded are using. If the addressing modes do not match, messages will not be decoded, **even if the address is otherwise a match.**

## **CAN ID**

Selects the CAN ID which will be used to receive the message. This may be either a decimal value or a hexadecimal value. Hexadecimal values are specified using the prefix "0x". For example, the (hexadecimal) channel ID 500h may be entered as either 0x500 or 1280 in the CAN configuration software.

## **Filter location**

It is possible to use one byte of the message as a filter, when a byte is selected for the filter location, only messages which have the correct filter value will be used.

## **Filter value**

Used in conjunction with filter location to enable message reception only when the byte specified in filter location matches this value.

## **Start bit**

The location of the first bit of the data to be received. Ranges from 0-63.

## **Length**

Total number of bits in the message, from 1-32.

## **Value type**

Select signed, unsigned or floating point. Floating point values are as defined in the IEEE754 Format.

## **Byte order**

Select from the following byte orders:

Intel Standard	Motorola forward MSB
Intel Sequential	Motorola sequential
Motorola forward LSB	Motorola backward

For more information on these formats, see the appendix Byte Ordering.

## **Scale factor**

A factor by the output value will be divided before being sent out through the serial port.

## **Offset**

A value which is added to the output value before it is output. (scale factor is applied before offset)

## **Loading and saving files**

From the file menu you can select to load or save data files.

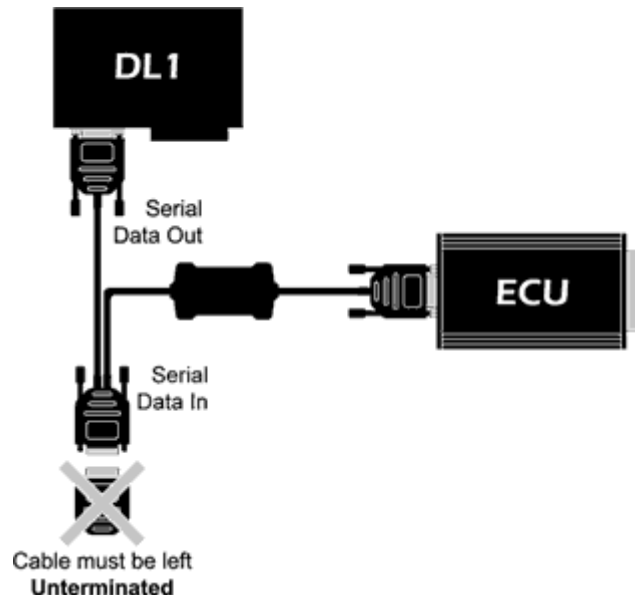
## Connecting the CAN Interface

There are several different ways in which the CAN interface can be used:

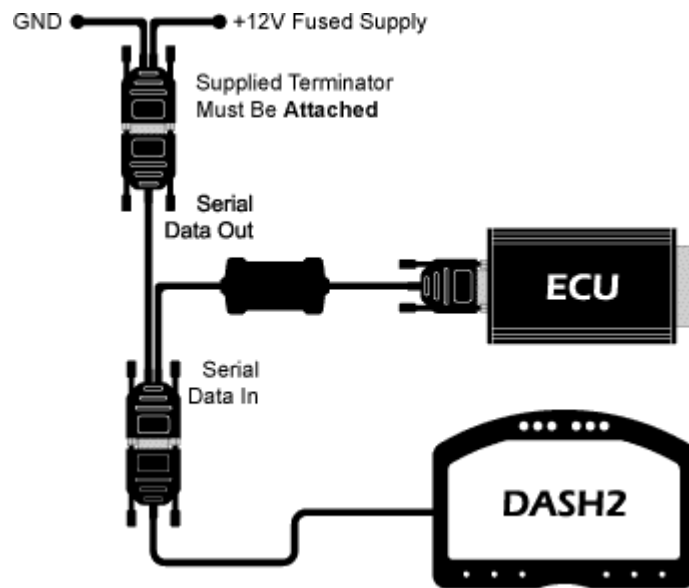
1. With DL1 or DL2 data logger and ECU
2. With DASH2 display (in standalone mode) and ECU
3. With DL1 or DL2, and DASH1 or DASH2, and ECU
4. Connected to a PC compatible computer for re-flashing (only recommended when given explicit instructions to do so by Race Technology)
5. With DL1 and PC Monitor software
6. With PC Monitor software
7. VIDEO4 and CAN
8. VIDEO4, DL1 and CAN
9. VIDEO4, CAN and DASH2
10. VIDEO4, DL1, CAN and DASH2
11. Daisy Chaining Devices

The connections for each type of installation are shown in the following illustrations.

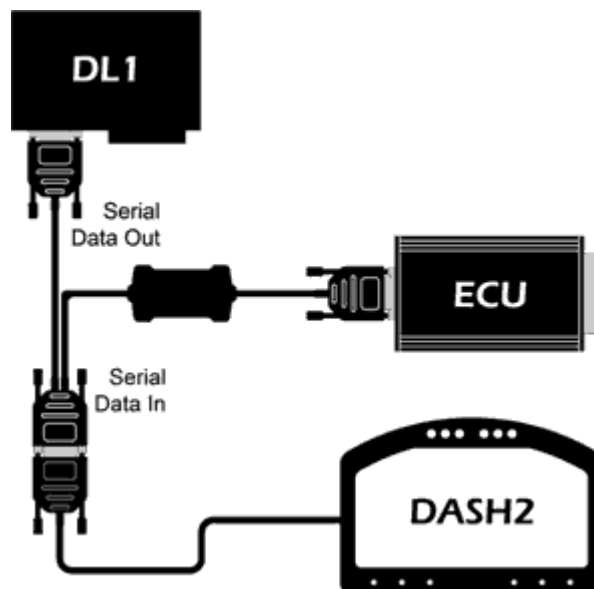
### 1. DL1 or DL2 Data Logger Only



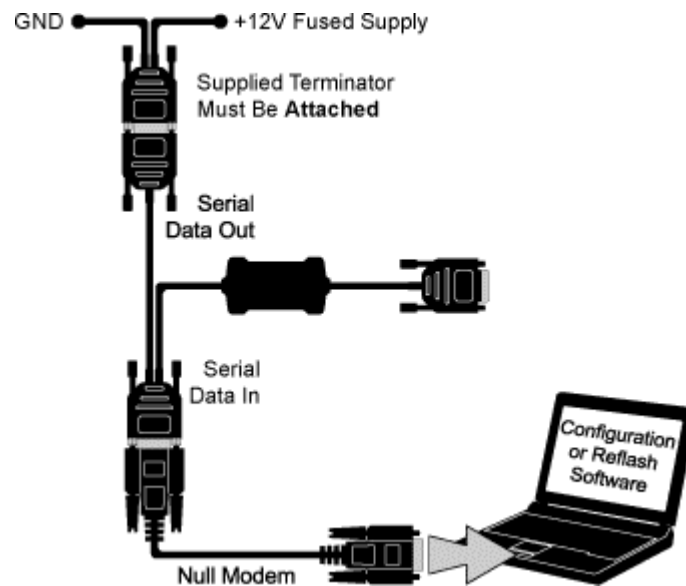
## 2. DASH2 Display Only



## 3. Data Logger and Display



## 4. PC Compatible Computer for Reflashing



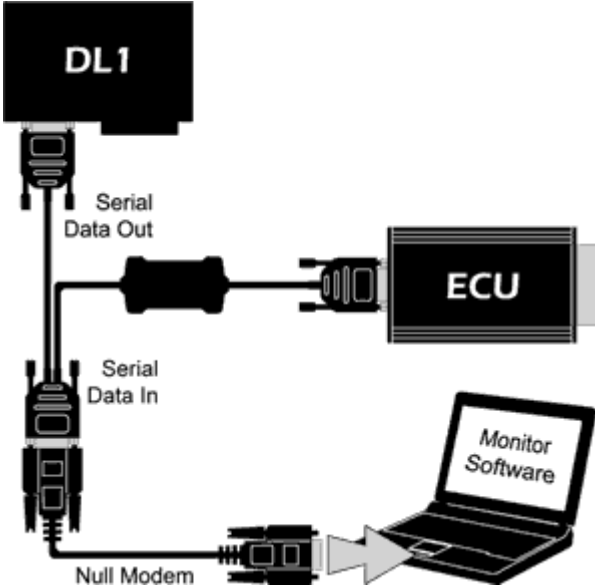
### Re-flashing Procedure

After connecting the CAN serial interface as shown above, ensure that the power to the unit is initially turned off. Use the Reflash Utility provided with the Race Technology software to reflash the unit. This is normally found from the Windows start menu by following programs \ Race Technology v7 \ Reflash. Then follow the on screen instructions provided by the Reflash Utility.

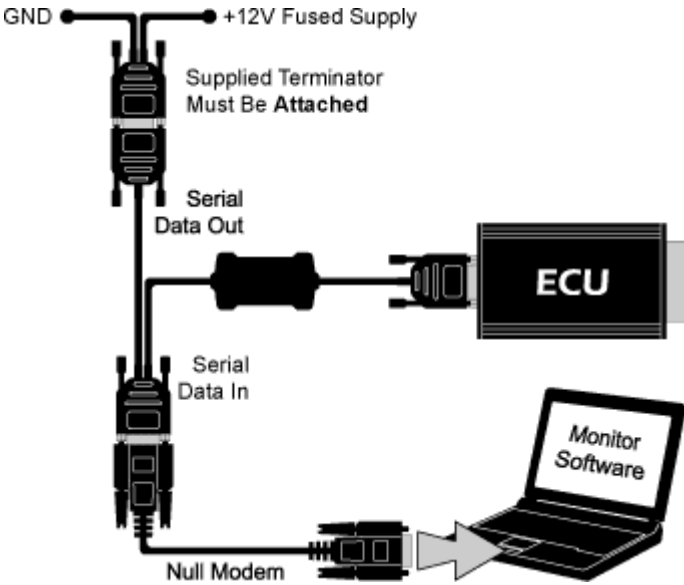
**WARNING: Only reflash the CAN serial interface if specifically instructed to do so by Race Technology. Any malfunction due to re-flashing without observing this warning will result in the warranty being void.**



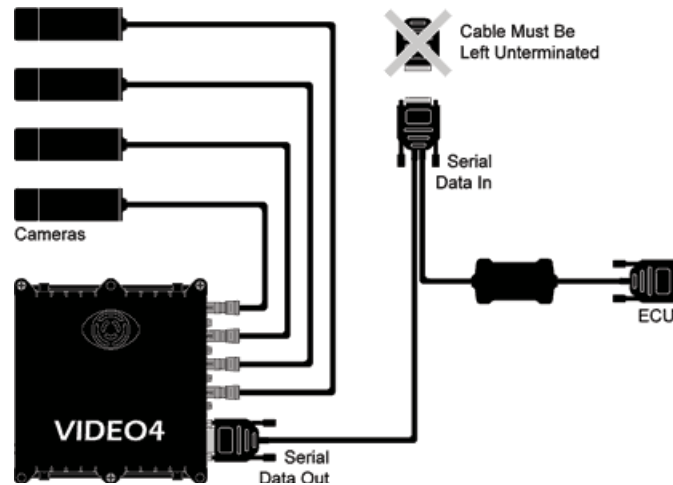
**5. DL1 and PC monitor**



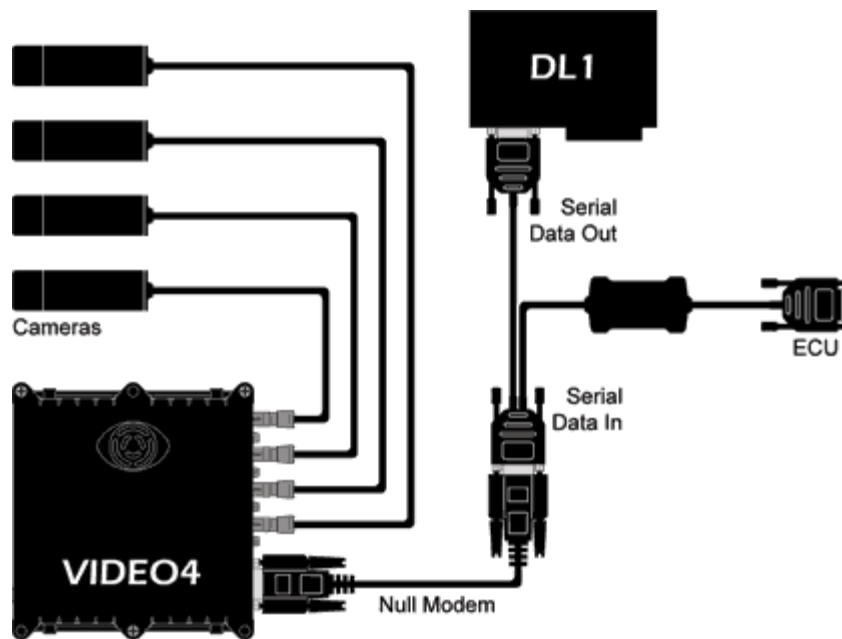
**6. PC monitor only**



## 7. VIDEO4 and CAN



## 8. VIDEO4, DL1 and CAN

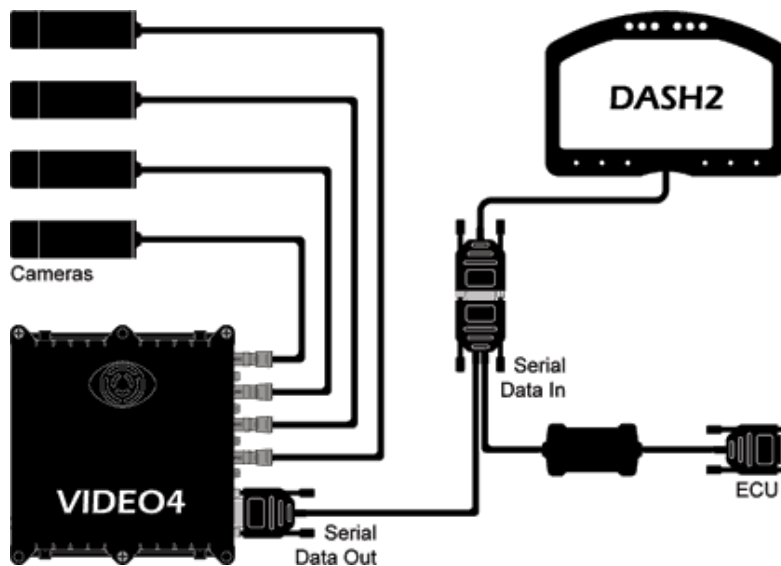


Please note that in this configuration it is important that both the DL1 and the VIDEO4 are configured to work together correctly. There is more information about this on the following web pages:

<http://www.race-technology.com/wiki/index.php/UnitConfigurations/VIDEO4ConfigForDL1>

<http://www.race-technology.com/wiki/index.php/UnitConfigurations/DL1ConfigForVIDEO4>

## 9. VIDEO4, CAN and DASH2



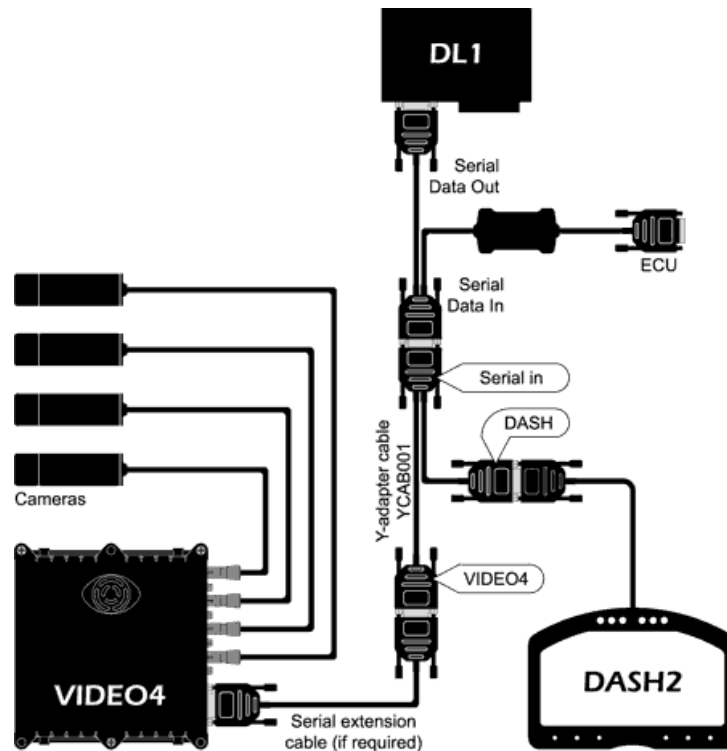
Please note that in this configuration it is important that both the DASH display and the VIDEO4 are configured to work together correctly. There is more information about this on following web page:

<http://www.race-technology.com/wiki/index.php/UnitConfigurations/VIDEO4ConfigForDASH>

**IMPORTANT:** When connecting a dashboard to a VIDEO4, it must be running firmware that has been published since the release of the VIDEO4 so it correctly decode the new VIDEO4 data. In particular:

- DASH1s must be running firmware version 9.1.5 or later
- DASH2s must be running firmware version 9.1.5 or later
- DASH3s must be running firmware version 1.31.18 or later

## 10. VIDEO4, DL1, CAN and DASH2



Please note that in this configuration it is important that both the DL1, DASH display and the VIDEO4 are configured to work together correctly. There is more information about this on these web pages:

<http://www.race-technology.com/wiki/index.php/UnitConfigurations/DL1ConfigForVIDEO4>

<http://www.race-technology.com/wiki/index.php/UnitConfigurations/VIDEO4ConfigForDASH>

## 11. Daisy Chaining Devices

CAN interface units can be daisy-chained by connecting the output of the first unit to the input of the second unit.

## **Configuring a Data Logger to work with the Interface**

To enable a DL1 or DL2 data logger to decode the information from interface, the data logger must be using Version 9 firmware or later. To find the firmware version, load a run file from your data logger into the Analysis software and use the Data / Run Manager menu to read information from the run data. In the information section the firmware version should be given as 9-4 or similar. The first number is the firmware revision number. If the firmware is earlier than this please contact Race Technology to obtain the latest firmware upgrade. This is available free of charge and can be re-flashed onto your data logger from your PC

Under normal circumstances the DL1 or DL2 does not try to decode the data it receives over the serial port, it simply stores the data onto the memory card. To enable the decoding of the data when using the CAN/ECU serial interface, start the data logger configuration program and make sure that the "Decode Serial Data" box is ticked and set the serial port speed to 115200 baud, then upload these new configuration settings to the data logger. The data will now be decoded at the correct speed, as it is being received from the ECU.

This data can either be saved to the memory card or sent out again over the serial port. If the data logger is used with a dashboard and you wish to view the ECU variables on the dashboard, ensure that "Incoming serial data" is enabled in the "Update Rates" section for the serial port, using the data logger configuration software. For storage to the CF card ensure that the "Incoming serial data / memory card" option is also enabled. These settings can all be accessed via the data logger configuration software.

Save the SETUP.BIN file on to the CF card and put it in to the data logger. From now on, the data logger will decode the incoming data and store it in the normal data stream.

## **Connection to a PC Compatible Computer for Reflashing**

See page 8 for connection and configuration procedure for re-flashing the CAN interface.

## ***Appendix A. Channel Names***

### **Temperature channels**

Default scaling is 0.1°C per bit.

Ambient Air Temperature  
Inlet Pre Turbo Temperature 1  
Inlet Pre Turbo Temperature 2  
Inlet Post Turbo Temperature 1  
Inlet Post Turbo Temperature 2  
Inlet Post Intercooler Temperature 1  
Inlet Post Intercooler Temperature 2  
Water Temperature  
Oil Temperature  
Gearbox Temperature  
Gearbox Temperature Post Cooler  
Tyre Temperature 1  
Tyre Temperature 2  
Tyre Temperature 3  
Tyre Temperature 4  
ECU Temperature  
Exhaust Temperature 1  
Exhaust Temperature 2  
Exhaust Temperature 3  
Exhaust Temperature 4  
Exhaust Temperature 5  
Exhaust Temperature 6  
Exhaust Temperature 7

Exhaust Temperature 8  
Auxiliary Temperature

### **Frequency channels**

Default scaling is 0.1Hz per bit

RPM Frequency RPM  
EGR Frequency EGR  
ISBV Frequency ISBV  
Nitrous Solenoid Frequency

### **Percentage channel data**

Default units for percentage channels are 0.1%

Throttle Position Percent  
Lambda 1 Short Term Trim Percent  
Lambda 2 Short Term Trim Percent  
Lambda 1 Long Term Trim Percent  
Lambda 2 Long Term Trim Percent  
Fuel Injector 1 Pulse Width Percent  
Fuel Injector 2 Pulse Width Percent  
Fuel Injector 3 Pulse Width Percent  
Fuel Injector 4 Pulse Width Percent  
Fuel Injector 5 Pulse Width Percent

Fuel Injector 6 Pulse Width Percent  
Fuel Injector 7 Pulse Width Percent  
Fuel Injector 8 Pulse Width Percent  
Fuel Injector 1 Cut Level Percent  
Fuel Injector 2 Cut Level Percent  
Fuel Injector 3 Cut Level Percent  
Fuel Injector 4 Cut Level Percent  
Fuel Injector 5 Cut Level Percent  
Fuel Injector 6 Cut Level Percent  
Fuel Injector 7 Cut Level Percent  
Fuel Injector 8 Cut Level Percent  
Ignition Cut Level Percent  
ISBV 1 Open Percent  
ISBV 2 Open Percent  
Nitrous Oxide Percent  
Auxiliary 1 Percent  
Auxiliary 2 Percent  
Auxiliary 3 Percent  
Auxiliary 4 Percent

Fuel Auxiliary Temperature Compensation  
Percent

Fuel Aux Volt Comp Percent

### **Time channel data**

**The default units for time channels are ms.**

For all time channels there is an additional scaling value which provides additional scaling in the format output = value x 10<sup>y</sup>.  
Where -5 < y < 5

Injector 1 On Time

Injector 2 On Time

Injector 3 On Time

Injector 4 On Time

Injector 5 On Time

Injector 6 On Time

Injector 7 On Time

Injector 8 On Time

Coil 1 Charge Time

Coil 2 Charge Time

Coil 3 Charge Time

## Appendix B. Byte Ordering

There are six options available for the ordering of the bytes. These different methods will be demonstrated with an example of a 12 bit channel in a 32 bit (4 byte) message.

### Bit ordering within the message

There are two methods of bit numbering in common usage, sequential and sawtooth. For a two byte method, saw tooth numbering would be as follows:

Byte 1	Byte 2
7 6 5 4 3 2 1 0	15 14 13 12 11 10 9 8

Sequential numbering would be:

Byte 1	Byte 2
0 1 2 3 4 5 6 7	8 9 10 11 12 13 14 15

### Intel Standard

7	6	5	4	3	2	1	0	
								0
<...	....	....	....	lsb				1
msb	....	....	....	....	....	....	....	2
								3

Start position of the signal (lsb, sawtooth): 11



## Intel Sequential

0	1	2	3	4	5	6	7	
								0
<....	....	....	....	lsb				1
msb	....	....	....	....	....	....	....	2
								3

Start position of the signal (lsb, monotone): 12

## Motorola forward LSB

7	6	5	4	3	2	1	0	
								0
				msb	....	....	....	1
<...	....	....	....	....	....	....	lsb	2
								3

Start position of the signal (lsb, sawtooth): 16

## Motorola forward MSB

7	6	5	4	3	2	1	0	
								0
				msb	....	....	....	1
<...	....	....	....	....	....	....	lsb	2
								3

Start position of the signal (msb, sawtooth): 11

## Motorola sequential

0	1	2	3	4	5	6	7	
								0
				msb	....	....	....	1
<...	....	....	....	....	....	....	lsb	2
								3

Start position of the signal (lsb, sawtooth): 12

## Motorola backward

7	6	5	4	3	2	1	0	
								0
				msb	....	....	....	1
<...	....	....	....	....	....	....	lsb	2
								3

Start position of the signal (lsb, sawtooth): 8

## ***Appendix C. Pin connections***

### **Serial Data In Connector**

9 Way Male D-Type

PIN 2 RS232 Input

PIN 3 RS232 Pass through

PIN 5 Ground

PIN 7 Power

### **Serial Data Out Connector**

9 Way Female D-Type

PIN 2 RS232 Output

PIN 3 RS232 Pass through

PIN 5 Ground

PIN 7 Power

### **CAN Connector**

9 Way Male D-Type

PIN 2 CAN Low

PIN 7 CAN High

## ***Appendix D. Physical parameters***

Dimensions: 35 x 24 x 8mm

Mass: Approx 85g

Cable lengths: Approx 25cm

Power supply: 9-16V @40mA

Sealing: Main body to IP67, Connectors to IP44

Operating Temp: 0-70°C